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**ADAPTIVE
IDENTIFICATION IN TORII
IN TRIANGULAR GRIDS**

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Adaptive Identification in Torii in Triangular Grids

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Abstract

Adaptive identification consists in asking the questions one after the other, allowing one to choose the next question according to the answers received so far, and its goal is to identify a (possible) faulty vertex in a graph. One can view adaptive identification also as a game, with the first player secretly choosing a vertex to be faulty, or no vertex at all, and the second player trying to locate the faulty vertex by asking questions of the type “is there a faulty vertex in the ball $B(v)$ center at some vertex v ?” for vertices in graph G . The goal of the first player is to maximize the number of needed queries and the goal of the second player is to minimize this number. In this paper we study adaptive identification in torii in the triangular lattice.

1 Introduction

Adaptive identification was introduced by Julien Moncel in his PhD thesis [10] and studied generally in [1], where in particular it has also been studied in torii in the square lattice.

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In [2] it has been studied in torii in the king lattice. Adaptive identification presents a dynamic variation of the classical static variant called identifying codes, which have been introduced in [9] with a purpose of fault diagnosis in multiprocessor systems.

Identifying code of a graph G is a subset of vertices C such that each vertex of G belongs to a ball centered at some member of C , and for each pair u, v of vertices, there is a ball centered at some member of C , which includes exactly one of u, v . Suppose we have a faulty vertex in a graph G , a graph with identifying code C . Then we can ask simultaneously all members of C if there is a faulty vertex in the balls center at them. From these questions the existence of identifying code C allows us to uniquely determine a faulty vertex, if it exist. After the introduction of identifying codes they have been widely studied, see [14] for a dynamic up-to-date online bibliography on identifying codes and related problems, edited by Antoine Lobstein.

If for a graph G with n vertices there exist an identifying code, then the minimum size of identifying code can be bounded below by $\lceil \log_2(n+1) \rceil$, see [11] for graphs attaining this bound and it can be bounded above by $n-1$, see [3] for graphs attaining this bound. Hence in the worst case we need at most $n-1$ questions to identify a faulty vertex using an identifying code in a graph in which an identifying code exist. The idea of adaptive identification is in asking the questions one after the other, instead of posing them simultaneously as in the case of identifying codes, and allowing one to choose the next question according to the answers received so far. One of the main features, as shown in [1] of adaptive identification is that it can significantly reduce the number of questions.

Adaptive identification can be also interpreted as a two players game, where one player choose a faulty vertex or no vertex at all, and the other player tries to identify a possible faulty vertex by asking questions as described above. In this sense adaptive identification is closely related to a Rényi-type search problem studied by Ruszinkó in [13] and by Ben-Haim and coauthors in [1, 2].

Next we define an infinite graph called triangular grid. The vertex set of the triangular grid T consist of the set $V = \left\{ i(1, 0) + j \left(\frac{1}{2}, \frac{\sqrt{3}}{2} \right); i, j \in \mathbb{Z} \right\}$ and there is an edge between any two vertices at distance one. Static identifying codes and some related invariants were already studied in this lattice, see [4, 5, 6, 7, 8].

The paper is structured as follows: the next section presents all necessary definitions and introduces notations needed in what follows. Section 3 brings main results about adaptive identification in torii in the triangular lattice, namely it presents bounds and exact values for adaptive identification in torii in the triangular lattice, as well as an illustrative example.

2 Basic definitions and notations

For a connected graph $G = (V, E)$, an integer $r \geq 1$, we denote by $B_r(v)$ the r -ball centered at $v \in V$, where $B_r(v) = \{x \in V \mid d(x, v) \leq r\}$ and $d(x, v)$ denotes the geodetic distance between vertex x and vertex v . Two vertices x and y are called r -twins in G if $B_r(x) = B_r(y)$. A graph is called r -twin-free if it has no pair of twin vertices.

A code C is a nonempty subset of vertices of V , and its elements are called codewords. If $x \in B_r(v)$, we say that x and v r -cover each other. If every vertex in some subset $X \subseteq V$ is r -covered by at least some vertex from Y , we say that a set X is r -covered by a set Y . A code D is called an r -dominating set if $B_r(x) \cap D \neq \emptyset$ for every $x \in V$. A code S r -separates two vertices x and y of V , if $B_r(x) \cap S \neq B_r(y) \cap S$. A code S is an r -separating set if it r -separates all pairs of distinct vertices of V . A code which is both r -dominating and r -separating, is called an r -identifying code. If all r -balls centered at vertices of a code C are pairwise disjoint, C is called an r -packing. A code which is both an r -covering code and an r -packing is called an r -perfect code.

Fundamental observation about r -identifying codes is that, for a given graph G and an integer $r \geq 1$, there exists an r -identifying code if and only if G is r -twin-free. Then we also say that G is r -identifiable graph.

For an r -identifiable graph G let $i_r(G)$ denote the minimum cardinality of an r -identifying code of G . Let $c_r(G)$ (resp. $\gamma_r(G)$) denote the maximum cardinality (resp. the minimum cardinality) of an r -packing of graph G (resp. of an r -covering code in graph G). Denote by $a_{(r,\leq l)}(G)$ maximum number of questions needed to identify at most l faulty vertices in r -identifiable graph G . When $l = 1$ we simplify the notation $a_{(r,\leq 1)}(G)$, and just write instead $a_r(G)$. For an r -regular graph G such that all r -balls of G are of the same cardinality, we denote the cardinality of its r -ball by $v_r(G)$. By $d_r(G)$ we denote the minimum number of questions needed to identify an r -ball in G . In other words by $d_r(G)$ we denote the minimum number of questions needed for identifying any given r -ball B in G , where we assume that there is no faulty vertex outside B .

We recall Theorem 1 from [1] which we need in the sequel.

Theorem 1. *Let $r \geq 1$ and let G be an r -regular r -identifiable graph. Then we have*

$$c_r(G) - 1 + \lceil \log_2(v_r(G) + 1) \rceil \leq a_r(G) \leq \gamma_r(G) - 1 + d_r(G).$$

3 Bounds and exact values for adaptive identification in torii in triangular grid

Given two integers p and q , the $p \times q$ torus in the triangular lattice, denoted by $T_{p,q}$, is the graph having vertex set

$$V = \{(i, j); 0 \leq i \leq p - 1, 0 \leq j \leq q - 1\}$$

and edge set $E = \{\{(i, j), (i, j + 1)\}, \{(i, j), (i + 1, j)\}, \{(i, j), (i + 1, j + 1)\}; 0 \leq i \leq p - 1, 0 \leq j \leq q - 1\}$, with sums on the first coordinate carried modulo p , and sums on the second coordinate carried modulo q .

In triangular grid 1-ball has cardinality 7, see Fig. 1. While r -ball in triangular grid has a shape of hexagon. In this hexagon we have $2r + 1$ rows. The cardinality of the middle row is $2r + 1$, continuing above and below, every next row has cardinality which is one less then the cardinality of the preceding row, see Fig. 2 for $r = 3$. The last row has

cardinality $r + 1$. Hence we get the following calculation for the cardinality of an r -ball in a triangular grid:

$$v_r(T_{p,q}) = 2 \cdot \sum_{i=r+1}^{2r} i + (2r + 1) = 2 \cdot \left(\frac{2r(2r + 1)}{2} - \frac{r(r + 1)}{2} \right) + 2r + 1 = 3r^2 + 3r + 1.$$

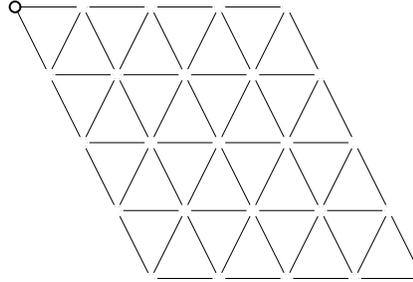


Figure 1: 1-ball in $T_{p,q}$.

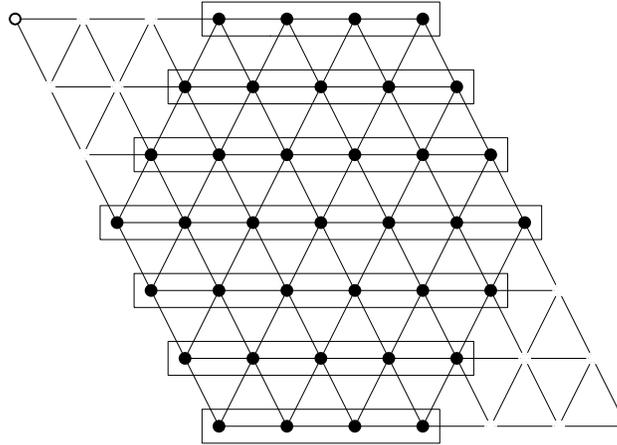


Figure 2: 3-ball in $T_{p,q}$ consists of 7 rows.

If p and q are both divisible by $3r^2 + 3r + 1$, then there exist a perfect code in a graph $T_{p,q}$. Graph $T_{p,q}$ has $p \times q$ vertices. If p and q are both divisible by $3r^2 + 3r + 1$, then also the number $p \times q$ is divisible by $3r^2 + 3r + 1$. It follows that $T_{p,q}$ contains $\frac{p \times q}{v_r(T_{p,q})}$ pairwise disjoint r -balls. In this case we have $c_r(T_{p,q}) = \gamma_r(T_{p,q})$.

Theorem 2. *Let $p, q \geq 7$ and let both p and q be divisible by 7, and let $T_{p,q}$ be a $p \times q$ torus in the triangular lattice. Then*

$$a_1(T_{p,q}) = \frac{pq}{7} + 2.$$

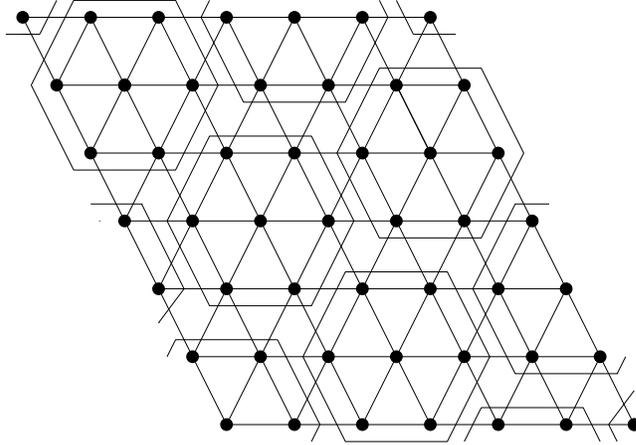


Figure 3: 1-perfect code in $T_{7,7}$

Proof. Since p and q are both divisible by 7, there exist a 1-perfect code in $T_{p,q}$. There are altogether $\frac{pq}{7}$ pairwise disjoint r -balls. To identify an r -ball with the faulty vertex, if the faulty vertex exist, we need at most $\frac{pq}{7} - 1$ queries. Because if for the first $\frac{pq}{7} - 1$ queries about whether there is a faulty vertex in a particular r -ball we receive answer NO, we continue with queries in the last ball. Suppose the faulty vertex, if it exists, is in the ball $B_1(x, y)$. We can always identify it with 3 queries as follows:

- Question 1: Is there a faulty vertex in $B_1(x - 1, y - 1)$?
 - YES, question 2: Is there a faulty vertex in $B_1(x - 1, y - 2)$?
 - YES, question 3: Is there a faulty vertex in $B_1(x - 2, y - 1)$?
 - YES, the faulty vertex is $(x - 1, y - 1)$.
 - NO, the faulty vertex is $(x, y - 1)$.
 - NO, question 3: Is there a faulty vertex in $B_1(x - 2, y)$?
 - YES, the faulty vertex is $(x - 1, y)$.
 - NO, the faulty vertex is (x, y) .
 - NO, question 2: Is there a faulty vertex in $B_1(x + 1, y + 2)$?
 - YES, question 3: Is there a faulty vertex in $B_1(x, y + 2)$?
 - YES, the faulty vertex is $(x, y + 1)$.
 - NO, the faulty vertex is $(x + 1, y + 1)$.
 - NO, question 3: Is there a faulty vertex in $B_1(x + 2, y)$?
 - YES, the faulty vertex is $(x + 1, y)$.
 - NO, there is no faulty vertex in the graph.

□

For a $T_{p,q}$, a $p \times q$ torus in the triangular lattice, let us denote by $Q_r(x, y)$ question, whether r -ball $B_r(x, y)$ (the r -ball centered in the vertex with coordinates (x, y)) contains a faulty vertex, and with $AQ_r(x)$ the answer to this question.

Lemma 3. *Let $r \geq 1$, $p, q \geq 3$ and let $T_{p,q}$ be a $p \times q$ torus in the triangular lattice. Then*

we have

$$\lceil \log_2(3r^2 + 3r + 2) \rceil \leq d_r(T_{p,q}) \leq 2\lceil \log_2(r + 1) \rceil + 3.$$

Proof. For the lower bound we have $3r^2 + 3r + 1$ different choices for a faulty vertex if there exists one, hence the bound follows from the general lower bound for a dichotomic search in a set of cardinality $3r^2 + 3r + 1$.

Suppose the faulty vertex belongs to the ball $B_r(x, y)$. Let us start with a question $Q_r(x - r, y - r)$. If $AQ_r(x - r, y - r) = \text{YES}$, then we have to consider vertices that belong to a subgraph, which is of a rhombic shape and consists of $(r + 1) \times (r + 1)$ vertices. To identify a faulty vertex in this rhomb we need at most $2\lceil \log_2(r + 1) \rceil$ questions. If $AQ_r(x - r, y - r) = \text{NO}$, then as a second question we choose $Q_r(x + r, y + r)$. If the answer to the second question is YES, then again we have to consider vertices that belong to a subgraph, which is of a rhombic shape and consists of $(r + 1) \times (r + 1)$ vertices, and we need at most $2\lceil \log_2(r + 1) \rceil$ questions. We have already used two additional questions, which altogether brings $2\lceil \log_2(r + 1) \rceil + 2$ questions. If $AQ_r(x + r, y + r) = \text{NO}$, two subgraphs of a shape of an equilateral triangle remain, where sides in both triangles consist of $r - 1$ vertices. With the third question we decide which of both triangles contains a faulty vertex. We can consider the triangle then as a rhomb with side $r - 1$, for which we need at most $2\lceil \log_2(r - 1) \rceil$ questions to identify a faulty vertex. If the answer to the third question is NO, we cannot know whether there exist a faulty vertex in the remaining triangle, but this makes us no problem. In the last row we have only one vertex and we can check with one question whether it is faulty. Altogether we need $2\lceil \log_2(r - 1) \rceil + 3$ questions, which is less than the claimed upper bound from the theorem. \square

The next two lemmata will be useful to determine how much the lower and the upper bound from Lemma 3 can differ. Both of them can be easily proved by induction and the proofs are left to the reader.

Lemma 4. For $r = 1$ and for $r = 2^m - s$, where $1 \leq s \leq 2^{m-2}$ and $m \geq 2$, we have

$$\lceil \log_2(2r^2 + 2r + 2) \rceil = 2\lceil \log_2(r + 1) \rceil + 1.$$

Lemma 5. For $r = 2^m + s$, where $0 \leq s \leq 2^{m-1}$ and $m \geq 2$, we have

$$(2\lceil \log_2(r + 1) \rceil + 1) - \lceil \log_2(2r^2 + 2r + 2) \rceil \in \{0, 1\}.$$

From Lemma 4 and Lemma 5 and since $\lceil \log_2(2r^2 + 2r + 2) \rceil \leq \lceil \log_2(3r^2 + 3r + 2) \rceil$ and $(2\lceil \log_2(r + 1) \rceil + 3) - (2\lceil \log_2(r + 1) \rceil + 1) = 2$, it follows $(2\lceil \log_2(r + 1) \rceil + 3) - \lceil \log_2(3r^2 + 3r + 2) \rceil \in \{0, 1, 2, 3\}$.

Example 6. For $r = 2$ the lower bound equals $\lceil \log_2 20 \rceil = 5$, and the upper bound equals $2\lceil \log_2 3 \rceil + 3 = 7$. Suppose the faulty vertex, if it exists, belongs to $B_2(x, y)$. Suppose $AQ_2(x - 2, y - 2) = \text{NO}$ and $AQ_2(x + 2, y + 2) = \text{YES}$. From this it follows that a faulty vertex belongs to 3×3 rhombus, which consists of nine vertices. Since $\lceil \log_2 9 \rceil = 4$, we need at most 4 queries to identify a faulty vertex in the rhombus. Altogether this means 6

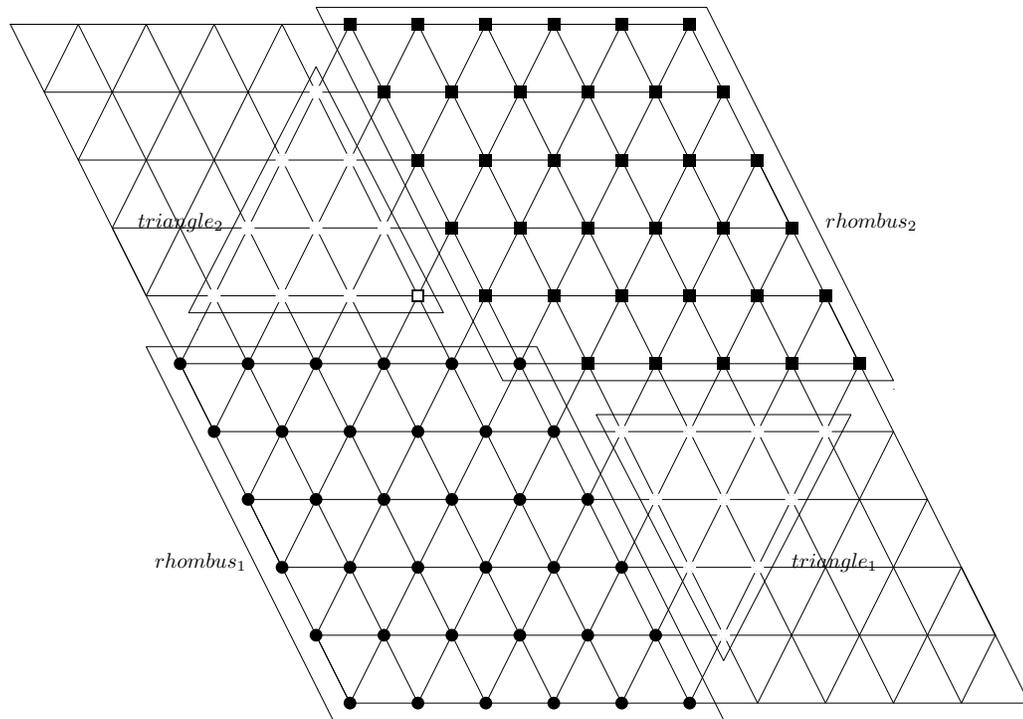


Figure 4: 5-ball in $T_{p,q}$ consist of two 6×6 rhombi and two equilateral triangles with sides of length 4.

queries, which means that the lower bound cannot be reached. But, from $Q_2(x-2, y-2) = \text{NO}$, we can deduce that a vertex (x, y) is not faulty. Vertex (x, y) is contained in the 3×3 rhombus, which is determined by the second question and we need to inquire only 8 vertices, which can be done with at most three questions, since $\log_2 8 = 3$. Let us now consider inquiry of $B_2(x, y)$ with five questions, which is the lower bound for $r = 2$.

- Question 1: Is there a faulty vertex in $B_2(x-2, y-2)$?
 - YES, question 2: Is there a faulty vertex in $B_2(x-3, y-3)$?
 - YES, question 3: Is there a faulty vertex in $B_2(x-1, y+1)$?
 - YES, question 4: Is there a faulty vertex in $B_2(x+1, y-1)$?
 - YES, the faulty vertex is $(x-1, y-1)$.
 - NO, the faulty vertex is $(x-2, y-1)$.
 - YES, question 4: Is there a faulty vertex in $B_2(x+1, y-2)$?
 - YES, the faulty vertex is $(x-1, y-2)$.
 - NO, the faulty vertex is $(x-2, y-2)$.
 - NO, question 3: Is there a faulty vertex in $B_2(x, y+2)$?
 - YES, question 4: Is there a faulty vertex in $B_2(x-1, y+2)$?
 - YES, question 5: Is there a faulty vertex in $B_2(x+1, y)$?
 - YES, the faulty vertex is $(x-1, y)$.

- NO, the faulty vertex is $(x - 2, y)$.
- NO, the faulty vertex is (x, y) .
- NO, question 4: Is there a faulty vertex in $B_2(x, y + 1)$?
 - YES, the faulty vertex is $(x, y - 1)$.
 - NO, the faulty vertex is $(x, y - 2)$.
- NO, question 2: Is there a faulty vertex in $B_2(x + 2, y + 2)$?
 - YES, question 3: Is there a faulty vertex in $B_2(x + 3, y + 3)$?
 - YES, question 4: Is there a faulty vertex in $B_2(x + 1, y - 1)$?
 - YES, question 5: Is there a faulty vertex in $B_2(x - 1, y + 1)$?
 - YES, the faulty vertex is $(x + 1, y + 1)$.
 - NO, the faulty vertex is $(x + 2, y + 1)$.
 - NO, question 5: Is there a faulty vertex in $B_2(x - 1, y + 2)$?
 - YES, the faulty vertex is $(x + 1, y + 2)$.
 - NO, the faulty vertex is $(x + 2, y + 2)$.
 - NO, question 4: Is there a faulty vertex in $B_2(x + 1, y - 2)$?
 - YES, question 5: Is there a faulty vertex in $B_2(x - 1, y)$?
 - YES, the faulty vertex is $(x + 1, y)$.
 - NO, the faulty vertex is $(x + 2, y)$.
 - NO, question 5: Is there a faulty vertex in $B_2(x, y - 1)$?
 - YES, the faulty vertex is $(x, y + 1)$.
 - NO, the faulty vertex is $(x, y + 2)$.
- NO, question 3: Is there a faulty vertex in $B_2(x + 1, y - 1)$?
 - YES, the faulty vertex is $(x + 1, y - 1)$.
 - NO, question 4: Is there a faulty vertex in $B_2(x - 1, y + 1)$?
 - YES, the faulty vertex is $(x - 1, y + 1)$.
 - NO, there is no faulty vertex in the graph.

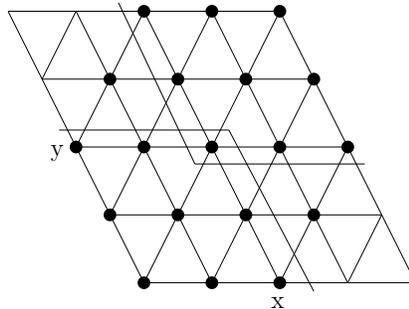


Figure 5: 2-ball in $T_{p,q}$, which contains two rhombi of size 3×3 . The central vertex (x, y) is contained in both rhombi.

Theorem 7. *Let p and q be divisible by $3r^2 + 3r + 1$ and let $T_{p,q}$ be a $p \times q$ torus in the triangular lattice. Then we have*

$$\frac{pq}{3r^2 + 3r + 1} - 1 + \lceil \log_2(3r^2 + 3r + 2) \rceil \leq a_r(T_{p,q}) \leq \frac{pq}{3r^2 + 3r + 1} + 2 \lceil \log_2(r + 1) \rceil + 2.$$

Proof. Since both p and q are divisible by $3r^2 + 3r + 1$, there exist a r -perfect code in $T_{p,q}$, which means $c_r(T_{p,q}) = \gamma_r(T_{p,q})$. Thus there are $\frac{pq}{3r^2+3r+1}$ pairwise disjoint r -balls in $T_{p,q}$, which cover all the vertices. Hence to identify r -ball with the faulty vertex, if such a vertex exists, we need at most $\frac{pq}{3r^2+3r+1} - 1$ questions. Since if the first $\frac{pq}{3r^2+3r+1} - 1$ questions receive a NO answer, then we continue with queries in the remaining r -ball. The proof follows from Lemma 3 and Theorem 1. \square

So far we have considered only cases where there might be at most one faulty vertex. In what follows we take a look at cases where there might be at most two faulty vertices.

Theorem 8. *Let $p, q \geq 14$ and let p and q be both divisible by 7. Then we have*

$$a_{(1,\leq 2)}(T_{p,q}) \leq \frac{pq}{7} + 7.$$

Proof. Since p and q are divisible by 7, there exist a 1-perfect code in $T_{p,q}$, where we have $\frac{pq}{7}$ pairwise disjoint 1-balls covering all the vertices in a graph. Hence we need at most $\frac{pq}{7}$ queries to identify the ball with faulty vertices. The following situations might occur:

- (1) Answers to all questions are NO. Then we know that in $T_{p,q}$ there is no faulty vertex.
- (2) One of the questions receives a YES answer. A 1-ball in $T_{p,q}$ consist of seven vertices, hence we can check for each of them if there is faulty vertex or not, no matter if there is only one or there are two faulty vertices, bringing all together at most 7 additional questions.
- (3) Two questions receive a YES answer. Then we know that both of this 1-balls contain exactly one faulty vertex. To determine a faulty vertex in any of those 1-balls we then need at most 3 questions, which brings altogether 6 questions. Also when these 1-balls are adjacent, there is no problem, since we can identify a faulty vertex in one ball without a question which covers some vertex from the other ball. \square

Returning to (2) from the previous proof. Suppose we have have one or two faulty vertices in the 1-ball $B_1(x, y)$ and let us start with $Q_1(x-1, y-1)$. If $AQ_1(x-1, y-1) = \text{NO}$, then we need at most three additional questions. If $AQ_1(x-1, y-1) = \text{YES}$, we continue with $Q_1(x+1, y+2)$. If $AQ_1(x+1, y+2) = \text{YES}$, we need one more additional question to determine whether a faulty vertex is $(x, y+1)$ or $(x+1, y+1)$. And we need two additional questions to determine which of the vertices $(x-1, y-1)$, $(x-1, y)$, $(x, y-1)$ and (x, y) are faulty. Altogether this means 5 questions. If $AQ_1(x+1, y+2) = \text{NO}$, we continue with $Q_1(x+2, y)$. If $AQ_1(x+2, y) = \text{YES}$, then one of the two faulty vertices is identified. The second faulty vertex can then be determined as in the first example. Altogether this means 5 questions. If $AQ_1(x+2, y) = \text{NO}$, we have to check the following vertices $(x-1, y-1)$, $(x-1, y)$, $(x, y-1)$ and (x, y) . In this case we don't know whether we have one or two faulty vertices. Hence we need 3 additional questions. Altogether this means 7 questions. This is the only case where we achieve the upper bound $\frac{pq}{7} + 7$.

Remark 9. For $l \geq 3$ a graph $T_{p,q}$ is not $(r, \leq l)$ -identifiable graph, see Fig. 6.

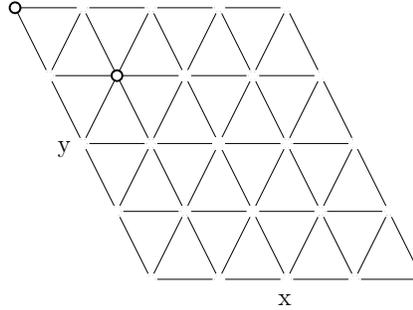


Figure 6: Suppose that in $T_{p,q}$ there are at most 3 faulty vertices and suppose that vertices with coordinates $(x, y - 1)$ and $(x, y + 1)$ are already known to be faulty. In this case there is no question which would determine whether a vertex (x, y) is a faulty vertex or not.

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